Physics 3A – Midterm 3 Review

Prof. Laszlo Bardoczi

Torque and Rotational Dynamics

$$\tau = rF \sin \theta$$

Concepts:

- Torque measures how effectively a force causes rotation.
- Depends on lever arm r and angle θ between r and F. In most of our applications, the arm and the force are perpendicular to each other, making $\theta = 90^{\circ}$ and hence $\sin(\theta) = 1$, leaving $\tau = rF$

$$\tau = I\alpha$$

Concepts:

- Rotational version of F = ma.
- *I* (moment of inertia) = resistance to rotational acceleration.

Torque Applications from Lecture Slides

Child pushing a merry-go-round

Tangential force creates torque: $\tau = FR$. (p3a_lec_7.2.pdf, slide 7)

Two children on a seesaw

Opposing torques: $\tau_{\text{net}} = m_2 g l_2 - m_1 g l_1$. (p3a_lec_7.2.pdf, slide 8)

Seesaw imbalance determining rotation direction

Compare left vs right torques. (p3a_lec_7.2.pdf, slide 16)

Rod released from the horizontal

Gravity produces torque: $\tau = mg\frac{L}{2}$. (p3a_lec_7.2.pdf, slide 10)

Bucket pulling a rotating disk

Rope tension causes torque: $\tau = TR$. (p3a_lec_7.2.pdf, slide 12)

Yo-yo unwinding while falling

Torque from tension drives rotation: $TR = I\alpha$. (p3a_lec_7.2.pdf, slide 15)

Rod-spool system driven by falling mass
 Rope tension applies torque on the spool to rotate the system.

(p3a_lec_7.2.pdf, slide 13)

Circular Motion & Angular Quantities (1/2)

Period and Frequency

$$f=\frac{1}{T}$$

- Period T = time for one revolution.
- Frequency f = number of revolutions per second.

Speed in Circular Motion

$$v = \frac{2\pi r}{T} = 2\pi r f$$

- Speed depends on radius and rate of rotation.
- Example: edge speed on a centrifuge rotor.



Circular Motion & Angular Quantities (2/2)

Angular Speed

$$\omega = 2\pi f$$

- Angular speed: radians per second.
- Links linear motion to rotational motion.

Angular Kinematics

$$\phi = \omega t$$
 and $\omega = {\rm const.}$ (uniform rotation) $\phi = \omega_0 t + {1\over 2} \alpha t^2$ (accelerating rotation) $\omega = \omega_0 + \alpha t$ (accelerating rotation)

Rotational analogs of constant-acceleration equations.

Examples from Lecture Slides (1/2)

Period & Frequency

- Car on a circular track, London Eye, spinning bicycle wheel (p3a_lec_7.1.pdf, slide 1)
- Table saw blade (compute T and f) (p3a_lec_7.1.pdf, slide 3)
- Quasar carnival ride finding rotation period (p3a_lec_7.1.pdf, slide 10)

Speed in Circular Motion ($v = 2\pi rf$ **)**

- Table saw blade speed of a tooth at the rim (p3a_lec_7.1.pdf, slide 3)
- Quasar carnival ride riders' speed using $v = \sqrt{ar}$ (p3a_lec_7.1.pdf, slide 10)

Angular Speed ($\omega = 2\pi f$)

- Circular motion coordinates: $x(t) = r\cos(\omega t)$, $y(t) = r\sin(\omega t)$ (p3a_lec_7.1.pdf, slide 8)
- Table saw blade rpm \rightarrow frequency \rightarrow angular speed (p3a_lec_7.1.pdf, slide 3)

Examples from Lecture Slides (2/2)

Angular Kinematics ($\omega = \omega_0 + \alpha t$, $\phi = \omega t$, ...)

- Merry-go-round pushed by a child torque $\to \alpha \to \text{final } \omega$ (p3a_lec_7.2.pdf, slide 7)
- Rod released from horizontal gravity torque gives angular acceleration (p3a_lec_7.2.pdf, slide 10)
- Yoyo unwinding tension creates α leading to changing $\omega(t)$ (p3a_lec_7.2.pdf, slide 15)

What is the Centripetal Force?

The centripetal force is not a new or mystical force.

It is simply the **net force that makes an object follow a circular path**. Even if the **speed stays constant**, the velocity is changing direction, and a change in velocity requires a force. The centripetal force is the inward force that provides the needed acceleration

$$a=\frac{v^2}{r}.$$

Which real force acts as the centripetal force depends on the situation:

- **Tension** (Tarzan swinging on a vine)
- Normal force (rollercoaster at the bottom of a loop)
- **Gravity** (rollercoaster at the top of a loop)
- Friction (car turning on a road)

Key idea: The centripetal force is the net inward force from the free-body diagram. It changes the direction of the velocity (not its magnitude) and always points toward the center of the circular path.

Moments of Inertia

Concepts:

- Rotational inertia depends on mass distribution.
- More mass farther from the axis \rightarrow larger I.
- Moments of inertia are listed on the equation sheet.
 You just need to recognize which one is which.

Momentum Basics

$$p = mv$$
 and $\frac{dp}{dt} = F(t)$

- Momentum measures "quantity of motion."
- Force changes momentum over time.

$$p_f - p_i = \int F(t)dt = J$$

- Impulse (J) = change in momentum.
- ullet Longer contact time o smaller force needed (e.g., padded shoes).

$$P_{\mathrm{tot}} = p_1 + p_2$$
 and $\Delta p_1 + \Delta p_2 = 0$

Internal forces in an isolated system cancel due to Newton's third law
 → total momentum stays constant.

Examples from Lecture Slides: Momentum Concepts

Momentum

- Golf club striking a ball large, short force changes momentum (p3a_lec_8.1.pdf, slide 1)
- Force—time graph during a collision momentum change equals area under F(t) (p3a_lec_8.1.pdf, slide 5)

Impulse

- Collision force modeled as a triangle computing F_{max} from impulse (p3a_lec_8.1.pdf, slide 11)
- Falling object impact impulse relates average impact force and fall height (p3a_lec_8.1.pdf, slide 13)

Momentum of a System

ullet Two blocks stuck together move with same v (p3a_lec_8.1.pdf, slide 14)

Momentum Conservation ($\Delta p_1 + \Delta p_2 = 0$)

- Collision of two balls Newton's 3rd law ⇒ equal and opposite momentum change (p3a_lec_8.1.pdf, slide 15)
- Example: Two colliding train cars stick together (p3a_lec_8.1.pdf, slide

Energy

- Kinetic energy (K) measures the energy of motion; potential energies
 (U) store energy based on position (height or spring compression).
- Total mechanical energy is conserved when no non-conservative forces (friction, drag) act on the system.
- Changes in energy tell you what the system can do—how fast it will move or how high it can rise.

$$K = \frac{1}{2}mv^{2}$$

$$U = mgh$$

$$U = \frac{1}{2}kx^{2}$$

$$E = K + U$$

Work

- Work is the process of transferring energy into or out of a system by applying a force over a distance.
- Only the component of force along the direction of motion contributes to work (recall properties of the dot product).
- Positive work increases the system's mechanical energy; negative work (like friction) removes mechanical energy and turns it into heat (energy, in general, is conserved).

$$W = Fx$$

$$W = \int F(x) dx$$

$$W = \Delta K$$

$$W = \Delta E$$

Power

- Power measures how fast work is done or how quickly energy is transferred.
- A large force doesn't guarantee high power—both force and speed matter.
- Human muscles have a maximum power output, which limits sprint speed and lifting performance.

$$P = \frac{dW}{dt} = Fv$$

Examples from Lecture Slides: Energy Concepts (1/2)

Kinetic and Potential Energy ($K = \frac{1}{2}mv^2$, U = mgh, $U = \frac{1}{2}kx^2$)

- Free—falling ball: gravitational potential → kinetic (p3a_lec_10.1.pdf, slide 11)
- Block sliding down frictionless slope conversion of U_g to K (p3a_lec_10.1.pdf, slide 11–12)
- Hooke's law spring compression stored spring potential energy (p3a_lec_10.1.pdf, slide 6)

Total Mechanical Energy (E = K + U)

- Conservative systems: ball in free fall, mass on a spring energy exchanges between K and U (p3a_lec_10.1.pdf, slide 10)
- Examples list: free fall, frictionless slope, simple harmonic oscillators (p3a_lec_10.1.pdf, slide 10)

Examples from Lecture Slides: Energy Concepts (2/2)

Work (
$$W = Fx$$
, $W = \int F(x)dx$, $W = \Delta K$, $W = \Delta E$)

- Work by gravity during vertical motion (p3a_lec_10.1.pdf, slide 6)
- Work done by friction (negative work, energy lost to heat)
 (p3a_lec_10.1.pdf, slide 6)
- Work done compressing a spring (requires integral) (p3a_lec_10.1.pdf, slide 6)
- Work–energy theorem ($W = \Delta K$) derived from $\int v \, dp$ (p3a_lec_10.1.pdf, slide 7)

Power
$$(P = dW/dt = Fv)$$

 Power in everyday activities: muscles doing work at a rate (see textbook)